Conformal Prediction with Missing Values

Margaux Zaffran 54èmes Journées de Statistiques, Bruxelles, 2023 Session MALIA





Aymeric Dieuleveut Ecole Polytechnique Paris - France





Yaniv Romano Technion - Israel Institute of Technology Haifa - Israel

What about splitting the data?

Standard Split Conformal Prediction for Mean-Regression Conformalized Quantile Regression

Predictive uncertainty quantification with missing values

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Split Conformal Prediction (SCP)^{1,2,3}: toy example



¹Vovk et al. (2005), Algorithmic Learning in a Random World ²Papadopoulos et al. (2002), Inductive Confidence Machines for Regression, ECML ³Lei et al. (2018), Distribution-Free Predictive Inference for Regression, JRSS B



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[▶] Predict with $\hat{\mu}$

- ► Get the |residuals|, a.k.a. scores ${S^{(k)}}_{k \in Cal}$
- Compute the (1α) empirical quantile of $S = \{|\text{residuals}|\}_{Cal} \cup \{+\infty\},\$ noted $q_{1-\alpha}(S)$

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Predict with \$\httt{\u03c0}\$
Build \$\hftac{C}_{\u03c0}(x)\$: [\$\u03c0(x) \pm q_{1-\u03c0}(S)\$]

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SCP theoretical foundation

Definition (Exchangeability)

 $(X^{(k)}, Y^{(k)})_{k=1}^{n}$ are exchangeable if for any permutation σ of [1, n] we have:

$$\mathcal{L}\left(\left(X^{(1)}, Y^{(1)}\right), \dots, \left(X^{(n)}, Y^{(n)}\right)\right) \\ = \mathcal{L}\left(\left(X^{(\sigma(1))}, Y^{(\sigma(1))}\right), \dots, \left(X^{(\sigma(n))}, Y^{(\sigma(n))}\right)\right),$$

where \mathcal{L} designates the joint distribution.

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Toy case: $Z^{(1)}$ and $Z^{(2)}$ are exchangeable if $(Z^{(1)}, Z^{(2)}) \stackrel{\mathcal{L}}{=} (Z^{(2)}, Z^{(1)})$.

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Examples of exchangeable sequences

• i.i.d. samples

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- i.i.d. samples
- ullet The components of ${\cal N}$

$$\begin{pmatrix} m \\ \vdots \\ \vdots \\ m \end{pmatrix}, \begin{pmatrix} \sigma^2 & & \\ & \ddots & \gamma^2 & \\ & \gamma^2 & \ddots & \\ & & & \sigma^2 \end{pmatrix} \end{pmatrix}$$

SCP enjoys finite sample guarantees proved in Vovk et al. (2005); Lei et al. (2018).

Theorem

Suppose $(X^{(k)}, Y^{(k)})_{k=1}^{n+1}$ are exchangeable (or i.i.d.). SCP applied on $(X^{(k)}, Y^{(k)})_{k=1}^{n}$ outputs $\widehat{C}_{\alpha}(\cdot)$ such that:

$$\mathbb{P}\left\{Y^{(n+1)}\in\widehat{C}_{\alpha}\left(X^{(n+1)}\right)\right\}\geq 1-\alpha$$

Additionally, if the scores $\{S^{(k)}\}_{k \in Cal}$ are a.s. distinct:

$$\mathbb{P}\left\{Y^{(n+1)} \in \widehat{C}_{\alpha}\left(X^{(n+1)}\right)\right\} \le 1 - \alpha + \frac{1}{\#\mathrm{Cal} + 1}$$

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X Marginal coverage: $\mathbb{P}\left\{Y^{(n+1)} \in \widehat{C}_{\alpha}\left(X^{(n+1)}\right) | X^{(n+1)} = x\right\} \ge 1 - \alpha$



Predict with \$\httype{\mu}\$
Build \$\hat{C}_{\alpha}(x)\$: [\$\httype{\mu}(x) \pm q_{1-\alpha}(\mathcal{S})\$]

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Conformalized Quantile Regression (CQR)⁴



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Data: $(X^{(k)}, Y^{(k)})_{k=1}^n$

Y	X_1	X_2	<i>X</i> ₃
22.42	0.55	0.67	0.03
8.26	0.72	0.18	0.55
19.41	0.60	0.58	NA
19.75	0.54	0.43	0.96
7.32	NA	0.19	NA
13.55	0.65	0.69	0.50
20.75	NA	NA	0.61
9.26	0.89	NA	0.84
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Mask $M =$			
$(M_1$	M_2	<i>M</i> ₃)	
0	0	0	
0	0	0	
0	0	1	
0	0	0	
1	0	1	
0	0	0	
1	1	0	

0 1 0 0 0 0

 $\hookrightarrow 2^d$ potential masks.

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$\hookrightarrow 2^d$ potential masks.

- $\hookrightarrow M$ can depend on X or Y.
- \Rightarrow Statistical and computational challenges.

Impute-then-regress procedures are widely used.

Supervised learning with missing values: impute-then-regress

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 \hookrightarrow we consider an impute-then-regress pipeline in this work.

Predictive uncertainty quantification with missing values

Goal: predict $Y^{(n+1)}$ with confidence $1 - \alpha$, i.e. build the smallest C_{α} such that:
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1. Marginal Validity (MV)

$$\mathbb{P}\left\{Y^{(n+1)} \in \mathcal{C}_{\alpha}\left(X^{(n+1)}, M^{(n+1)}\right)\right\} \ge 1 - \alpha.$$
 (MV)

For example: $\alpha = 0.1$ and obtain a 90% coverage interval.

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2. Mask-Conditional-Validity (MCV)

$$\forall m \in \{0,1\}^d : \mathbb{P}\left\{Y^{(n+1)} \in \mathcal{C}_{\alpha}\left(X^{(n+1)}, m\right) | M^{(n+1)} = m\right\} \ge 1 - \alpha.$$
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Ilustrations @theoremlinger

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3 considered approaches to reach these goals.

	Quantile Regression (QR)	
(MV)	?	
(MCV)	?	



• Marginal validity (eq. (MV), i.e. on average) is not reached!



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• The predictive uncertainty strongly depends on the mask

	QR	
(MV)	×	
(MCV)	×	



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 - \hookrightarrow missing values induce heteroskedasticity



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- \hookrightarrow missing values induce heteroskedasticity
- $\,\hookrightarrow\,$ supported by theory on the Gaussian Linear Model

Theoretical study of the Gaussian linear model $(Y = \beta^T X + \varepsilon)$ generalizes \hookrightarrow oracle intervals: smallest predictive interval when the distribution of Y|(X, M) is known

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Proposition (Oracle intervals under the Gaussian lin. mod.)

$$\mathcal{L}^*_{\alpha}(m) = 2 \times q_{1-\alpha/2}^{\mathcal{N}(0,1)} \times \sqrt{\beta_{\mathrm{mis}(m)}^{\mathcal{T}} \Sigma_{\mathrm{mis}|\mathrm{obs}}^m \beta_{\mathrm{mis}(m)} + \sigma_{\varepsilon}^2}$$

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- The uncertainty increases when missing values are associated with larger regression coefficients (i.e. the most predictive variables)

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Lemma

Assume $(X^{(k)}, M^{(k)}, Y^{(k)})_{k=1}^n$ are *i.i.d.* (or exchangeable).

Then, for any missing mechanism, for almost all imputation function¹ ϕ : $\left(\phi\left(X_{obs(M^{(k)})}^{(k)}, M^{(k)}\right), Y^{(k)}\right)_{k=1}^{n}$ are **exchangeable**.

¹Even if the imputation is not accurate, the guarantee will hold.

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 \Rightarrow CQR, and Conformal Prediction, applied on an imputed data set still enjoys marginal guarantees:

$$\mathbb{P}\left\{Y^{(n+1)} \in \widehat{C}_{\alpha}\left(X^{(n+1)}, M^{(n+1)}\right)\right\} \ge 1 - \alpha.$$

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CQR is marginally valid on imputed data sets



• Marginal (i.e. average) coverage is indeed recovered!

	QR	CQR	
(MV)	×	1	
(MCV)	×		

CQR is marginally valid on imputed data sets



• Disparities between masks is not corrected by the conformalization step.

	QR	CQR	
(MV)	×	 Image: A second s	
(MCV)	×	×	

Conformalization step is independent of the important variable: the mask!



Observation: the α -correction term is computed \succ among all the data points, regardless of their mask!

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Warning: 2^d possible masks

 \Rightarrow Splitting the calibration set by mask is infeasible (lack of data)!



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Missing Data Augmentation (MDA)

Idea: for each test point, modify the calibration points to mimic the test mask

Test point



Algorithms: MDA with Exact masking or with Nested masking.



- Split the training set into a proper training set and calibration set
- 2. Train the imputation function on the proper training set
- 3. Impute the proper training set

4. Train the quantile regressors on the imputed proper training set





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3	NA	NA	1
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$$j \in [\![1, d]\!]$$
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 - 5.4 Impute the test point
 - 5.5 Predict with the quantile regressors and the correction previously obtained, $q_{1-\alpha}(S)$



Theorem (CP-MDA-Exact achieves MCV)

If the data is exchangeable and $M \perp (X, Y)$, then for almost all imputation function CP-MDA-Exact is such that for any $m \in \{0, 1\}^d$:

$$\mathbb{P}\left(Y\in\widehat{\mathcal{C}}_{lpha}\left(X,m
ight)|M=m
ight)\geq1-lpha,$$

and if additionally the scores are almost surely distinct:

$$\mathbb{P}\left(Y \in \widehat{\mathcal{C}}_{\alpha}\left(X, m\right) | M = m\right) \leq 1 - \alpha + \frac{1}{1 + \# \mathrm{Cal}^{\mathrm{m}}}$$
MDA achieves Mask-Conditional-Validity (MCV), cont'd



MDA achieves Mask-Conditional-Validity in an informative way



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- Neural network, fitted to minimize the pinball loss
- (Semi)-synthetic experiments:
 - $\circ~$ MCAR missing values, with probability 20%
 - \circ 100 repetitions









Before more experiments, visualisation



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- $igstarrow : ext{highest coverage, i.e.} \ \max_{m \in \mathcal{M}} \mathbb{P}(Y \in \hat{C}_lpha(X,m) | M = m)$

























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 → Many useful statistical tasks

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These covariates are not always observed: from 0% to 24% of missing values by features, with a total average of 7%.

Real data experiment: TraumaBase[®], critical care medicine



What about splitting the data?

Predictive uncertainty quantification with missing values

Learning with Missing Data

Conformal Prediction with Missing Values

Missing Data Augmentation

Experimental Results

Conclusions
- Consistency of universal quantile learner when chained with almost any imputation function.
- CP-MDA-Nested, an algorithm which does not discard any calibration point.



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- Missing data augmentation attains conditional coverage with respect to the missing pattern (in MCAR setting).

Thanks for listening! Any question? :)

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